

# inkMaths

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ANSWER BOOK

## Kinematics with variable acceleration

Mechanics · Year 12–13

6 questions · 20 marks

NAVY EDITION

**SECTION A** · Warm-up

- A1** Suvat is derived assuming a constant: with a changing, its formulae are simply false. [2]  
Instead  $v = dx/dt$  and  $a = dv/dt$ , with integration running the chain backwards, constants fixed by the starting conditions.
- A2**  $a = dv/dt = 12t^2 - 6$ , so at  $t = 2$ ,  $a = 48 - 6 = 42 \text{ m s}^{-2}$ . One differentiation; the only care [3]  
needed is not to integrate by reflex instead.

**SECTION B** · Standard

- B1**  $a = 8 - 4t$  is zero at  $t = 2$ , where  $v = 16 - 8 = 8 \text{ m s}^{-1}$ : the maximum, since  $a$  is positive [4]  
before and negative after. Integrating,  $x = 4t^2 - (2/3)t^3$  (constant zero from the origin  
start), so  $x(3) = 36 - 18 = 18 \text{ m}$ . Maximum velocity comes from  $a = 0$ , not  $v = 0$ : the two  
conditions answer different questions.
- B2** Integrating:  $v = 3t^2 - 12t + c$ , and  $v(0) = 9$  gives  $c = 9$ . Factorising:  $v = 3(t - 1)(t - 3)$ , so the [4]  
particle is at rest at  $t = 1$  and  $t = 3$ . The initial condition pins the constant before  
anything else can be asked.
- B3**  $x = t^3 - 6t^2 + 9t$ . The displacement is  $x(3) - x(0) = 0$ : back where it started. But the [4]  
journey ran forward 4 m by  $t = 1$ , then backward 4 m by  $t = 3$ , so the distance travelled  
is 8 m. Splitting at the rest times is compulsory: integrating  $v$  straight through lets the  
two legs cancel.

**SECTION C** · Stretch

- C1**  $x(3) = 27 - 54 + 27 = 0$ , so it is at the origin, and  $v(3) = 0$ , so it is momentarily at rest [3]  
there too: back at the start, stationary, with  $a = 6 \text{ m s}^{-2}$  about to push it forward again.  
Factorising  $x = t(t - 3)^2$  shows the return written into the algebra: the squared bracket is  
the touch.